

Bringing Home Automation to the Raspberry Pi





User Manual

Version 1

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Table of Contents

1	Introduction	. 1
	1.1 Topics Covered	. 2
	1.2 Necessary components	. 2
2	Step by step installation of the Raspberry-Pi	. 3
	2.1 Installation of Raspian (Debian Linux for Raspberry-Pi)	. 3
	2.2 Basic configuration via "raspi-config"	. 3
	2.3 Software and Firmware update	. 4
	2.4 Connecting Raspberry-Pi and the EnOcean-Pi	. 4
	2.5 Discover the IP address of your Raspberry-Pi	5
	2.6 Remote control of your Raspberry-Pi	5
	2.6.1 Setting up PuTTY	5
	2.7 Installation of the building automation server	6
	2.7.1 Installation of the Perl environment including libraries for FHEM	; . 7
	2.7.2 Installation FHEM	. 7
	2.7.3 Display of the FHEM Web Interface	. 7
	2.7.4 Configuring the FHEM Server	. 8
	2.7.5 Configure the EnOcean-Pi:	. 8
	2.7.6 Configure the PTM switch:	. 8
	2.7.7 Configure the STM sensor:	. 9
	2.7.8 Visualization:	. 9
	2.8 Interpretation of EnOcean radio telegrams via the FHEM	•••
	event monitor	10
A	ppendix 1: Useful Links	11
	1.1 EnOcean radio modules:	11

1.2 element14 Raspberry Pi and accessories:1	1
1.3 Raspberry-Pi1	1
1.4 FHEM:	1

Appendix 2: Regulatory Compliance and Safety Information12

1 Introduction

This user guide shows how to integrate the EnOcean Sensor kit with the Raspberry Pi and EnOcean-Pi add-on board. The example is based around a home automation system but it can form the basis of many other IoT projects. It uses FHEM as the basis of the server but

Applicable Frequencies:			
	315MHz	Asia (excluding China)	
	868MHz	Europe (including China)	
	902MHz	USA	

other open systems are also available such as openHAB



Wireless, energy autonomous sensors and switches are ideal for home automation projects as no cabling is required. Sensors and actuators can directly communicate with each other or they can be controlled by an intelligent smart home server. This allows users to set up home automation for remote sensing and remote control via PC or smart phone. Raspberry-Pi is the ideal platform to setup a smart home server where the EnOcean-Pi acts as a bridge (Gateway-Controller) to the EnOcean radio world. We recommend using self-powered switches and sensors from the EnOcean starter kit *ESK300/ESK300U* or the Sensor Kit for Raspberry-Pi.



Figure 1: Home Automation Using Raspberry Pi & EnOcean Pi

Raspberry-Pi when used with FHEM server software becomes a home automation server. The server can be used to automate common tasks such as switching lamps, scene illuminations or closing blinds, measurement and visualization of power consumption, temperature and humidity.

The server receives and sends EnOcean radio telegrams via the EnOcean-Pi. The Solar powered radio sensors (STM330 temperature sensor & STM320 reed contact sensor) periodically send values which will be interpreted and displayed via the FHEM web interface. Self-powered switches and FHEM send on/off and dim commands to actuators (not included in the kit) or to a PiFace relay board (if connected)

1.1 Topics Covered

- Installation of Raspberry-Pi and preparation for smart home projects
- Connection of an EnOcean-Pi to Raspberry-Pi
- Installation of the FHEM server for home automation
- Configuration of FHEM for EnOcean switches, sensors and actuators contained in the Sensor Kits

1.2 Necessary components

- PC with internet browser
- EnOcean-Pi

• Sensor Kit

- Raspberry-Pi board (model B)
- Raspberry-Pi accessories:
 - $\circ~$ USB micro power supply $_{(\sim 1A)}$
 - HDMI cable
 - SD card (e.g. 4GB)
- Ethernet cable or USB WLAN stick



Figure 2: Top to Bottom - EnOcean-Pi, Sensor Kit, Raspberry Pi

2 Step by step installation of the Raspberry-Pi

2.1 Installation of Raspian (Debian Linux for Raspberry-Pi)

If the Raspian image is not already installed on the SD card, download NOOBS (New Out of the Box Software) and follow the instructions at:



2. Login with username ${\tt pi}$ and password ${\tt raspberry}$

3. The configuration menu should start automatically after booting, if not, just type sudo raspi-config

- 4. Select the following items to configure:
- 5. expand_rootfs to use the full SD card size
- 6. configure_keyboard to set the correct keyboard settings
- 7. change_timezone to set the correct time & date
- 8. change_location to allow for country specific characters etc.

1	Expand Filesystem	Ensures that all of the SD card storage is available to the OS
2	Change User Password	Change password for the default user (pi)
3	Enable Boot to Desktop	Choose whether to boot into a desktop environment or the command-lin
4	Internationalisation Options	s Set up language and regional settings to match your location
5	Enable Camera	Enable this Pi to work with the Raspberry Pi Camera
6	Add to Rastrack	Add this Pi to the online Raspberry Pi Map (Rastrack)
7	Overclock	Configure overclocking for your Pi
8	Advanced Options	Configure advanced settings
9	About raspi-config	Information about this configuration tool

Figure 3: Raspi-config Menu

2.3 Software and Firmware update

Prior to updating you need to connect to internet. This can be done in one of two ways:

1. Via Ethernet, plug into the connector and let the Raspberry Pi handle the rest

2. WiFi (if drivers are available), start the GUI (using the startx command) and click on WiFi config. Follow the on screen prompts.

Raspian (the Linux operating system) can be updated via APT (Advanced Package Tool).

RPi-update:

https://github.com/Hexxeh/rpi-update

is used to update the firmware (hardware driver) of Raspberry-Pi. In order to have an up to date system (e.g. to recognize the EnOcean-Pi) both updates are required.

Get the latest updates of Raspian and Raspberry Pi firmware:

```
sudo apt-get update
sudo apt-get upgrade
sudo apt-get install rpi-update
Then reboot:
```

NOTE:

Several shell commands need root (super user) rights; therefore "sudo" is used as a prefix.

sudo restart

2.4 Connecting Raspberry-Pi and the EnOcean-Pi

1. Connect EnOcean-Pi on top of Raspberry-Pi board via its connector



2. Disable Linux using the serial port

<u>L</u>

NOTE:

As default the serial port of the GPIO interface is used for console debug outputs. In order to use this port for EnOcean-Pi, this feature has to be disabled. Read more about this at:

http://elinux.org/RPi Serial Connection



A script can be downloaded from Github which will automatically adapt boot up settings:

```
https://github.com/lurch/rpi-serial-console
```

3. Download the script:

```
sudo wget https://raw.github.com/lurch/rpi-serial-console/master/rpi-
serial-console -0 /usr/bin/rpi-serial-console && sudo chmod +x
/usr/bin/rpi-serial-console
```

4. Execute the script:

sudo rpi-serial-console disable

5. You can test the connection via the FHEM event monitor (*Refer to section 2.8*)

2.5 Discover the IP address of your Raspberry-Pi

In most cases the IP address is provided via the DHCP server. For remote control via TTY (e.g. via PuTTY) or HTML server connections (FHEM server) the IP address of Raspberry-Pi is required.

You can discover the allocated (by the DHCP server) IP address by typing in the following command:

ifconfig

Example output:

pi@raspbe	rrypi ~ \$ ifconfig
eth0	Link encap:Ethernet HWaddr b8:27:eb:c3:32:73
	inet addr:192.167.1.121 Bcast:192.167.1.255 Mask:255.255.255.0
	UP BROADCAST RUNNING MULTICAST MTU:1500 Metric:1
	RX packets:1077688 errors:0 dropped:0 overruns:0 frame:0
	TX packets:68259 errors:0 dropped:0 overruns:0 carrier:0
	collisions:0 txqueuelen:1000
	RX bytes:119175561 (113.6 MiB) TX bytes:6098823 (5.8 MiB)

You can see that in this example output text the IP address is 192.167.1.121

2.6 Remote control of your Raspberry-Pi

If your desktop is too small for an additional Raspberry-Pi display screen and keyboard, remote control of your tiny computer is the best solution. This allows you to access the command line or Linux shell via an SSH client on the PC.

2.6.1 Setting up PuTTY

PuTTY is a virtual terminal which can receive and display the working information of the Raspberry Pi. It needs to be configured on your PC before it can communicate with the Raspberry Pi. Follow the steps listed below to ensure correct configuration.

Download "*putty.exe"* from:



to your PC and run it to open the **PuTTY Configuration** window then configure it as shown below, substituting the IP address (192.168.7.2) for the IP address you discovered in *section 2.5*

😵 PuTTY Configuration 🛛 💽 🗙		
Category:		
 Session Logging Terminal Keyboard Bell Features Window Appearance Behaviour Translation Selection Colours Connection Data Proxy Telnet Rlogin SSH Serial 	Basic options for your PuTTY session Specify the destination you want to connect to Host Name (or IP address) Port 192.168.7.2 22 Connection type: Rlogin ● SSH ● Serial Load, save or delete a stored session Saved Sessions Default Settings Load Default Settings Load Close window on exit: ● Only on clean exit	
<u>A</u> bout <u>H</u> elp	<u>D</u> pen <u>C</u> ancel	

Figure 4: PuTTY Configuration Settings

Click **Open** when you finish the configuration

Now you have a command line interface to remotely control your Raspberry Pi via PC

2.7 Installation of the building automation server

This example project uses the FHEM server available under a GPL license.

More details can be found on the FHEM website:



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2.7.1 Installation of the Perl environment including libraries for FHEM

1. FHEM runs as a server on a Perl interpreter, which needs to be installed.

```
sudo apt-get install perl libdevice-serialport-perl libio-socket-ssl-perl
libwww-perl
sudo apt-get install -f
```

2.7.2 Installation FHEM

1. Please check the FHEM website for the latest version and modify the installation commands below as required:

```
wget http://fhem.de/fhem-5.5.deb
sudo dpkg -i fhem-5.5.deb
```

2. FHEM has been installed within the folder /opt/fhem. It starts automatically.

Note:

 $\hfill\square$ Check the FHEM website for updates and any path changes in new versions.

2.7.3 Display of the FHEM Web Interface

Start your chosen internet browser and type the following to the address bar:

http://<Raspberry_Pi_IP>:8083/fhem
You will get the following user interface on the screen:



Figure 5: The FHEM Web Interface

FHEM automatically recognizes the EnOcean-Pi and receives radio telegrams from EnOcean devices. Additionally it generates by default device entities for each new received EnOcean ID. With the user interface you can visualize and configure graphical user elements to visualize events and send control telegrams to actuators.

A small "how to" guide can be found at:

http://fhem.de/HOWTO.html

For German users there is an additional forum available:



2.7.4 Configuring the FHEM Server

FHEM server is configured via the configuration file fhem.cfg.

Start the configuration file editor via the FHEM menu item "Edit files".



Figure 6: FHEM Server Configuration

A reference of FHEM commands for EnOcean can be found at:

http://fhem.de/commandref.html#EnOcean

2.7.5 Configure the EnOcean-Pi:

FHEM might not recognize the EnOcean-Pi as an EnOcean Gateway-Controller. To fix this you can manually enter following definition:

define TCM310 0 TCM 310 /dev/ttyAMA0@57600

2.7.6 Configure the PTM switch:

Click on PTM switch and you will get following entries (the ID may be different):

```
define EnO_switch_001396B9 EnOcean 001396B9
attr EnO_switch_001396B9 room EnOcean
attr EnO_switch_001396B9 subType switch
define FileLog_EnO_switch_001396B9 FileLog ./log/EnO_switch_001396B9-%Y.log
EnO_switch_001396B9
attr FileLog_EnO_switch_001396B9 logtype text
attr FileLog_EnO_switch_001396B9 room EnOcean
```

2.7.7 Configure the STM sensor:

Press learn button of STM330 sensor and you will get (the ID may be different):

```
define En0_contact_0181FA67 EnOcean 0181FA67
attr En0_contact_0181FA67 room EnOcean
attr En0_contact_0181FA67 subType contact
define FileLog_En0_contact_0181FA67 FileLog ./log/En0_contact_0181FA67-
%Y.log En0_contact_0181FA67
attr FileLog_En0_contact_0181FA67 logtype text
attr FileLog_En0_contact_0181FA67 room EnOcean
```

2.7.8 Visualization:

Following visualization example has been generated by an STM330 (temperature sensor) with a HSM 100 (humidity sensor) connected:

```
#ID:0088F03E STM_330 temperatur & humidty sensor
define Sensor_0088F03E EnOcean 0088F03E
attr Sensor_0088F03E manufID 00B
attr Sensor_0088F03E room EnOcean
attr Sensor_0088F03E subType roomSensorControl.01
define FileLog_EnO_sensor_0088F03E FileLog ./log/EnO_sensor_0088F03E-%Y.log
Sensor_0088F03E
attr FileLog_Sensor_0088F03E logtype text
attr FileLog Sensor 0088F03E room EnOcean
```



Figure 7: Temperature/Humidity Visualization

2.8 Interpretation of EnOcean radio telegrams via the FHEM event monitor

Start PuTTy and configure it to connect to the IP address of the Raspberry-Pi with telnet and port 7072. Switch on "implicit CR in every LF" within the terminal configuration to get a line feed after carriage return.

Real Putty Configuration	2	Reputty Configuration	<u>२</u>
Category:		Category:	
	Basic options for your PuTTY session Specify the destination you want to connect to Host Name (or IP address) Port 192.167.1.121 7072 Connection type: Rag Rag Telnet Rag Telnet Rogin SSH Save Segal Load, save or delete a stored session Saved Sessions Default Settings RPL, Home Rasp Quelete Close window on expt: Aways Never Only on clean exit	Session Session Session Session Session Session Sel Session Sel Session Sel Sehaviour Selection Selection Selection Solution Selection Solution Selection Solution Selection Selection Selection Selection Selection Selection Selection Solution Selection Solution Selection Selectio	Options controlling the terminal emulation Set various terminal options ✓ Auto wrap mode initially on DEC Origin Mode initially on ✓ Implicit CF in every LF Implicit CF in every CR ✓ Usg background colour to erase screen Epable blinking text Angwerback to ^E: PuTTY Line discipline options Local echo: ④ Auto Force on Force off Local line editing: ④ Auto Force on Force off Remote-controlled printing Printer to send ANSI printer output to: None (printing disabled)
About <u>H</u> elp	<u>Open</u>	About <u>H</u> elp	<u>Open</u> <u>Cancel</u>

Figure 8: PuTTY Telnet Configuration

Start a telnet session and type inform timer to display the FHEM event monitor. Receiving events with EnOcean telegrams will be shown with a time stamp.

Putty 192.167.1.121 - Putty	
2013-08-08 16:31:34	EnOcean EnO sensor 00035DF4 sensor3: 89
2013-08-08 16:31:34	EnOcean EnO sensor 00035DF4 D3: 1
2013-08-08 16:31:34	EnOcean EnO_sensor_00035DF4 D2: 1
2013-08-08 16:31:34	EnOcean EnO_sensor_00035DF4 D1: 1
2013-08-08 16:31:34	EnOcean EnO_sensor_00035DF4 D0: 1
2013-08-08 16:31:37	Global global UNDEFINED EnO_sensor_0080D2E9 EnOcean 0080D2E9
2013-08-08 16:31:37	Global global DEFINED EnO_sensor_0080D2E9
2013-08-08 16:31:37	Global global SAVE
2013-08-08 16:31:37	EnOcean EnO_sensor_0080D2E9 148
2013-08-08 16:31:37	EnOcean EnO_sensor_0080D2E9 sensor1: 148
2013-08-08 16:31:37	EnOcean EnO_sensor_0080D2E9 sensor2: 122
2013-08-08 16:31:37	EnOcean EnO_sensor_0080D2E9 sensor3: 0
2013-08-08 16:31:37	EnOcean EnO_sensor_0080D2E9 D3: 1
2013-08-08 16:31:37	EnOcean EnO_sensor_0080D2E9 D2: 1
2013-08-08 16:31:37	EnOcean EnO_sensor_0080D2E9 D1: 1
2013-08-08 16:31:37	EnOcean EnO_sensor_0080D2E9 D0: 1
2013-08-08 16:31:38	Global global UNDEFINED EnO_contact_00003FC6 EnOcean 00003FC
6	
2013-08-08 16:31:38	Global global DEFINED EnO_contact_00003FC6
2013-08-08 16:31:38	Global global SAVE
2013-08-08 16:31:38	EnOcean EnO_contact_00003FC6 open
2013-08-08 16:31:38	EnOcean EnO_contact_00003FC6 learnBtn: on
2013-08-08 16:31:44	EnOcean EnO_sensor_00035DF4 0
	· · · · · · · · · · · · · · · · · · ·

Figure 9: FHEM Event Monitor

Appendix 1: Useful Links

1.1 EnOcean radio modules:



1.2 element14 Raspberry Pi and accessories:



1.3 Raspberry-Pi



1.4 FHEM:



Appendix 2: Regulatory Compliance and Safety Information

The Sensor Kits are available in several frequency variants:

SENSOR KIT 868 (868MHz for Europe, including China) includes: STM 330 / STM3 329 / PTM 210

SENSOR KIT 315 (315MHz for Asia, excluding China) includes: STM 330C / STM 320C / PTM 200C

SENSOR KIT 902 (902MHz for US / Canada) includes: STM 330U / STM 320U / PTM 210U

WARNINGS:

- Devices or Modules containing RF components must meet the essential requirements of the local legal authorities.
- The modules must not be used in any relation with equipment that supports, directly or indirectly, any form of life or with applications that can endanger life or value.
- Any changes or modifications not expressly approved by the party responsible for compliance may 'void' the user's authority to operate this equipment
- These modules must not be modified or used outside of their specification limits
- These modules may only be used to transfer digital or digitized data; Analogue speech and/or music is not permitted
- The modules must not be used with gain antennas, otherwise resulting in exceeded ERP or spurious emission levels.

COMPLIANCE INFORMATION:

The **Sensor Kit for Raspberry-Pi** complies with the relevant provisions of the RoHS Directive for the European Union.

WEEE Directive Statement for the European Union

- In common with all Electronic and Electrical products the Sensor Kit should not be disposed of in household waste within the European Union
- Components of the modules are considered and should be disposed of as hazardous waste.
- Alternative arrangements may apply to local jurisdictions.

EMC COMPLIANCE STATEMENTS:

European Union (EU) Electromagnetic Compatibility Directive Compliance Statement

This product is in conformity with the protection requirements of EU Council Directive 2004/108/EC on the approximation of the laws of the Member States relating to electromagnetic compatibility.

This product has been tested and found to comply with the limits for Class B Information Technology Equipment according to the European Standards EN 55022 & EN 55024.



FEDERAL COMMUNICATIONS COMMISSION (FCC) EMISSIONS COMPLIANCE STATEMENT

This equipment has been tested and complies with the limits f or a Class B digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a domestic environment.

Operation is subject to the following two conditions:

(1) this device might not cause harmful interference, and

(2) this device must accept any interference received, including interference that might cause undesired operation.

STM320C (315MHz) / STM320U (902MHz) / STM330 (868MHz) – Scavenger Transmitter Modules:

These modules have been tested to fulfil the approval requirements for CE and conform to the R&TTE (EN 300 220) EU-directive on radio equipment (for STM330) and (CFR-47 Part 15) FCC (for STM320C / STM320U) based on the built-in firmware.

PTM200C (315MHz) / PTM210U (902MHz) / PTM210 (868MHz) – Pushbutton Transmitter Devices:

These modules have been tested to fulfil the appropriate approval requirements for CE and conform to the R&TTE (EN 300 220) EU-directive on radio equipment and FCC (CFR-47 Part 15).

INDUSTRY CANADA EMISSIONS COMPLIANCE STATEMENT

This Class B digital apparatus complies with Canadian ICES-003. Cet appareil numérique de la classe B est conforme à la norme NMB-003 du Canada

Compliant with:



www.element14.com/legislation

Premier Farnell UK, 150 Armley Road, Leeds LS12 2QQ, United Kingdom Revision 1.1 April 2012